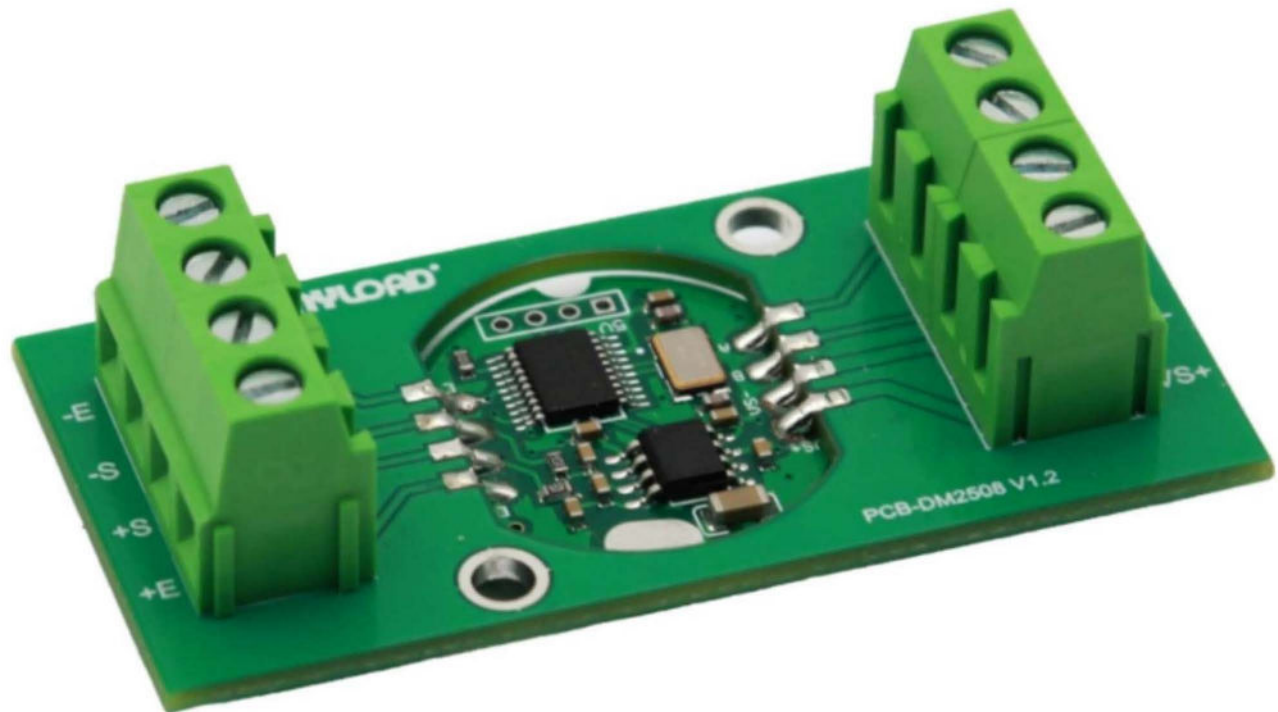




1-855-269-5623  
[www.anyload.com](http://www.anyload.com)

PN-250609

© ANYLOAD Weigh & Measure Inc. All rights reserved.

ANYLOAD® is a registered trademark of ANYLOAD Weigh & Measure Inc.

All other brand or product names mentioned in this document are trademarks or registered trademarks of their respective owners.

All information contained in this document is, to the best of our knowledge, complete and accurate at the time of publication. ANYLOAD Weigh & Measure Inc. reserves the right to make changes to the technology, features, specifications, and design of its equipment without prior notice.

The most current version of this document, along with any software, firmware, and other product updates, can be found on our website:

[www.anyload.com](http://www.anyload.com)

#### **Legal Notice**

ANYLOAD products are subject to our **Standard Terms and Conditions of Sale, Warranty Policy**, and applicable regulatory compliance requirements as they may be updated without notice. It is the user's responsibility to ensure proper installation, operation, and maintenance of the equipment as outlined in this manual and in accordance with all relevant laws and standards.

ANYLOAD Weigh & Measure Inc. disclaims all warranties not expressly stated in the Warranty Policy, including but not limited to implied warranties of merchantability and fitness for a particular purpose. ANYLOAD shall not be liable for any direct, indirect, incidental, or consequential damages arising from the use or inability to use this equipment.

# CONTENTS

---

|                                                |    |
|------------------------------------------------|----|
| CONTENTS .....                                 | 1  |
| 1. Introduction .....                          | 3  |
| 1.1 Features.....                              | 3  |
| 1.2 Safety.....                                | 3  |
| 2. Connection Diagram .....                    | 5  |
| 3. Installation.....                           | 5  |
| 3.1 Connecting Power and Signal Wires .....    | 5  |
| 3.2 Securing the Board .....                   | 5  |
| 4. Communication Protocol .....                | 6  |
| 4.1 Communication Examples.....                | 7  |
| 4.1.1 Reading Measurement Value .....          | 7  |
| 4.1.2 Setting Transmitter Device Address ..... | 8  |
| 4.1.3 Tare Weight .....                        | 8  |
| 4.1.4 Zero Setting .....                       | 8  |
| 5. Calibration .....                           | 9  |
| 6. Operation .....                             | 9  |
| 7. Compliance .....                            | 9  |
| 8. Technical Specifications .....              | 9  |
| 8.1 Drawings & Dimensions.....                 | 10 |
| 8.2 Specifications Table .....                 | 11 |

## Revision History:

---

Record with brief description of all revisions made to product or manual

| Version | Date                        | Description                   |
|---------|-----------------------------|-------------------------------|
| 1.0.0   | June 6 <sup>th</sup> , 2025 | First public release version. |
|         |                             |                               |
|         |                             |                               |
|         |                             |                               |
|         |                             |                               |
|         |                             |                               |
|         |                             |                               |

The most current version of this document, along with any software, firmware, and other product updates, can be found on our website:

[www.anyload.com](http://www.anyload.com)

# 1. Introduction

This manual provides information on installation, configuration, calibration and servicing of the DGB-DM2507/DM2508 Load Cell Amplifier.

For questions regarding this manual or the operation of ANYLOAD products, please contact your authorized ANYLOAD distributor or visit our website at [www.anyload.com](http://www.anyload.com) for support resources and service information.

## 1.1 Features

- Digital output options for RS-232 (DGB-DM2507) or RS-485 MODBUS RTU (DGB-DM2508)
- 24-bit A/D converter, high speed processor
- Sensor input range: 0.8~3.9mV/V
- Reverse polarity protection

## 1.2 Safety

READ this manual BEFORE operating or servicing this equipment or systems with this equipment incorporated.

FOLLOW these instructions carefully.

DO NOT allow untrained personnel to operate, clean, inspect, maintain, service, or modify this equipment.

SAVE and distribute this manual for future reference.

Failure to follow the instructions or heed the warnings could result in injury or death. Contact any ANYLOAD dealer or distributor for replacement manuals.

### Indicative Markings:

| Symbol                                                                                                                                                                                 | Significance                                                                                      |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|
|  <b>WARNING</b>  | Warns of a potentially dangerous situation which can result in serious physical injury or death   |
|  <b>CAUTION</b>                                                                                     | Warns of a potentially dangerous situation which can result in slight or moderate physical injury |
| <b>Notice</b>                                                                                                                                                                          | Failure to comply to information with this marking may lead to damage to property                 |
|  <b>Important</b>                                                                                   | Important information about the product                                                           |
|  <b>Tip</b>                                                                                         | Application tips and other information that may be helpful                                        |
| <i>For emphasis (Italics)</i>                                                                                                                                                          | Italics are used to emphasize key information                                                     |

## General Safety:

### ⚠ WARNING ⚠

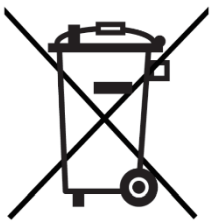
ONLY qualified professionals approved should carry out intrinsically safe installations. This work involves extensive knowledge of the product, specific safety standards, and the potentially hazardous environment in which it will be operating.

- Do not allow minors or inexperienced individuals to operate this unit.
- Ensure the unit is fully assembled before operation.
- Keep hands and fingers away from slots, openings, or any potential pinch points.
- Do not use this product if any component appears cracked or damaged.
- Avoid making alterations or modifications to the unit.
- Do not remove or obscure any warning labels.
- Do not submerge the unit in water.
- Before opening the unit, ensure the power cord is disconnected from the power source. Disconnect all power sources before servicing, as multiple power sources may be present. Failure to do so may result in property damage, personal injury, or death.
- For permanently connected equipment, incorporate a readily accessible disconnect device in the building's installation wiring.
- Pluggable units must be installed near an easily accessible socket/outlet.
- Use only copper or copper-clad aluminum conductors when wiring.

## Recommendations for Proper Use:

- Keep the instrument away from heat sources and direct sunlight.
- Protect the instrument from rain unless it is a special IP-rated version.
- Do not clean with water jets unless specified for IP-rated models.
- Avoid dipping the instrument in water or spilling liquids on it.
- Use a soft, dry cloth for cleaning; do not use solvents or abrasive materials.
- Do not install the unit in areas with explosion hazards unless with specially rated models.
- If the working environment reaches the unit's temperature limits, ensure proper airflow around the instrument to prevent malfunctions such as sudden shutdowns or disconnections.

## Disposal Guidelines:



Product Disposal: Dispose of this product at authorized waste collection centers at the end of its life cycle. Proper disposal prevents environmental and health risks and supports recycling. Illegal disposal may result in legal penalties.

Battery Disposal: Dispose of batteries at designated centers as per local laws. Batteries may contain harmful substances (e.g., Cd, Li, Hg, Pb) and must not be discarded with household waste. Improper disposal may result in legal penalties.

## 2. Connection Diagram

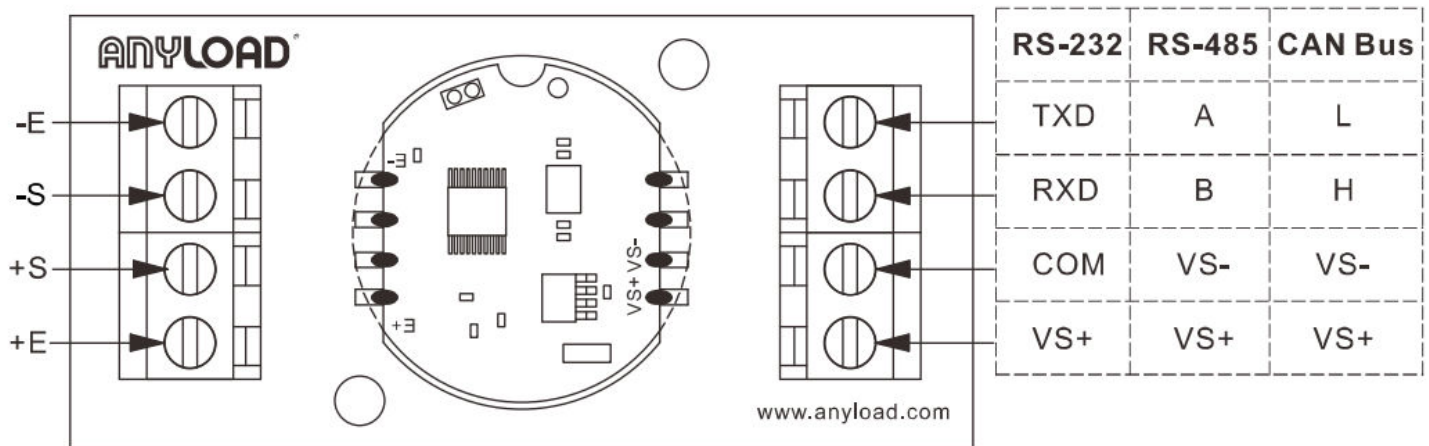


Figure 2-1: Connection Diagram for DGB-DM2507x/(2508x)

## 3. Installation

### 3.1 Connecting Power and Signal Wires

Connecting the power, output signal, and load cell to the amplifier can be accomplished with a small flat head screwdriver.

1. Loosen the terminals far enough that the lower section of the terminal clamp is visible.
2. Insert the loose, stripped wire into the terminal, ensure the wire remains near the top of the terminal hole.
3. Once the terminal is tightened, lightly check that the wires are clamped correctly and will not fall out of the terminal.

Note: If a wire is not clamped correctly, loosen the terminal again, and ensure the wire is inserted properly into the clamp assembly before tightening.

### 3.2 Securing the Board

The board includes two holes for M3 or 1/8" screws to secure it. Ensure that the board is being installed on appropriate height standoffs to provide adequate space for solder joints and components underneath the board once the assembly is fastened properly.

#### ⚠ CAUTION

Care must be taken when tightening the screws to not overtighten them as this can result in cracking or breaking the PCB.

## 4. Communication Protocol

Table 4-1: Modbus RTU Parameters and Holding Registers (MSB First)

| Parameter                  | Holding register (HEX) | Modbus Register (Decimal) | Operation Mode | Range      | Note                                          |
|----------------------------|------------------------|---------------------------|----------------|------------|-----------------------------------------------|
| Measuring Value            | 0000 & 0001            | 40001 & 40002             | R/W            | Int32      | Write to TARE or preset                       |
| Station id                 | 0002 & 0003            | 40003 & 40004             | R/W            | 1 to 254   | 0 reserved for broadcast                      |
| Offset Value               | 0004 & 0005            | 40005 & 40006             | R/W            | Int32      |                                               |
| Cal. Points num            | 0006 & 0007            | 40007 & 40008             | R/W            | 2 to 9     | # of calibration points, >2 for linearization |
| AVP1                       | 0008 & 0009            | 40009 & 40010             | R/W            | Int32      | #1 point AD input value                       |
| AVP2                       | 000A & 000B            | 40011 & 40012             | R/W            | int32      | #2 point AD input value                       |
| AVP3                       | 000C & 000D            | 40013 & 40014             | R/W            | int32      | #3 point AD input value                       |
| AVP4                       | 000E & 000F            | 40015 & 40016             | R/W            | int32      | #4 point AD input value                       |
| AVP5                       | 0010 & 0011            | 40017 & 40018             | R/W            | int32      | #5 point AD input value                       |
| AVP6                       | 0012 & 0013            | 40019 & 40020             | R/W            | int32      | #6 point AD input value                       |
| AVP7                       | 0014 & 0015            | 40021 & 40022             | R/W            | int32      | #7 point AD input value                       |
| AVP8                       | 0016 & 0017            | 40023 & 40024             | R/W            | int32      | #8 point AD input value                       |
| AVP9                       | 0018 & 0019            | 40025 & 40026             | R/W            | int32      | #9 point AD input value                       |
| PVP1                       | 001A & 001B            | 40027 & 40028             | R/W            | int32      | #1 point output value                         |
| PVP2                       | 001C & 001D            | 40029 & 40030             | R/W            | int32      | #2 point output value                         |
| PVP3                       | 001E & 001F            | 40031 & 40032             | R/W            | int32      | #3 point output value                         |
| PVP4                       | 0020 & 0021            | 40033 & 40034             | R/W            | int32      | #4 point output value                         |
| PVP5                       | 0022 & 0023            | 40035 & 40036             | R/W            | int32      | #5 point output value                         |
| PVP6                       | 0024 & 0025            | 40037 & 40038             | R/W            | int32      | #6 point output value                         |
| PVP7                       | 0026 & 0027            | 40039 & 40040             | R/W            | int32      | #7 point output value                         |
| PVP8                       | 0028 & 0029            | 40041 & 40042             | R/W            | int32      | #8 point output value                         |
| PVP9                       | 002A & 002B            | 40043 & 40044             | R/W            | int32      | #9 point output value                         |
| ADC Speed                  | 0034 & 0035            | 40053 & 40054             | R/W            | 0/1        | 10/ 40 SPS                                    |
| Filter Level               | 0056 & 0057            | 40087 & 40088             | R/W            | 0 to 5     | Bigger for stable but more delay              |
| Filter Band                | 0058 & 0059            | 40089 & 40090             | R/W            | 0 to 1000  | Filter effective band                         |
| Baud Rate                  | 005A & 005B            | 40091 & 40092             | R/W            | 0 to 10    | 300 to 115200bps, Table 2                     |
| Zero Trace Delay           | 005C & 005D            | 40093 & 40094             | R/W            | 0 to 50    | Times 100ms                                   |
| Zero Trace Band            | 005E & 005F            | 40095 & 40096             | R/W            | 0 to 10000 | Zero trace effective band                     |
| Stable Judgment Delay Time | 0060 & 0061            | 40097 & 40098             | R/W            | 1 to 50    | Times 100ms                                   |
| Stable Judgment Band       | 0062 & 0063            | 40099 & 40100             | R/W            | 1 to 100   | Times 1/2 output digits                       |
| Output Round               | 0064 & 0065            | 40101 & 40102             | R/W            | 1 to 250   |                                               |
| Parity                     | 0066 & 0067            | 40103 & 40104             | R/W            | 0 to 4     | Table 3                                       |
| AD value                   | 1F40 & 1F41            | 48001 & 48002             | R              | int32      | ADC raw value                                 |

**Default settings:**

- Baud rate: 9600bps (configurable)
- Start bit: 1
- Data bits: 8
- Parity: none (configurable)
- Stop bit: 1
- Station ID: 1 (1-254 available, 0 is reserved for broadcast)

*Table 4-2: Baud Rate*

| Value | Baud rate (bps) |
|-------|-----------------|
| 0     | 300             |
| 1     | 600             |
| 2     | 1200            |
| 3     | 2400            |
| 4     | 4800            |
| 5     | 9600            |
| 6     | 19200           |
| 7     | 28800           |
| 8     | 38400           |
| 9     | 57600           |
| 10    | 115200          |

*Table 4-3: Parity*

| Value | Parity |
|-------|--------|
| 0     | None   |
| 1     | Odd    |
| 2     | Even   |
| 3     | MARK   |
| 4     | SPACE  |

## 4.1 Communication Examples

### 4.1.1 Reading Measurement Value

Using Function Code (FC) 03, read the holding register. Measured values are stored in registers 0000-0001 (40001-40002) using a 32 bit signed integer value.

Note: The measured value register does not have support for decimal values so the conversion must be done manually. The value will be based on the resolution set during calibration. For example, an 800kg weight will read 800 000 if the resolution is set in grams (g).

Host sends: 01 03 00 00 00 02 C4 0B (Device address: 01, function code: 03, register address: 0000, register number: 02, CRC 16 bits: C4 0B)

Transmitter responds: 01 03 04 00 01 05 E2 28 EA (Device address: 01, function code: 03, data bytes: 4, measurement data: [00 01 05 E2] (equal to 67 042 in decimal, CRC 16 bits: 28 EA)

#### 4.1.2 Setting Transmitter Device Address

Using FC10, the original station ID can be changed from 01 in register 0002-0003 (40003-40004). As an example, here's how to change the station ID to 10.

Host sends: 01 10 00 02 00 02 04 00 00 00 0A F2 71 (Device address: 01, function code: 10, register address: 0002, register number: 02, data bytes: 04, new station ID: [00 00 00 0A] (equal to 10 in decimal), CRC 16 bits: F2 71)

Transmitter responds: 01 10 00 02 00 02 E0 08 (Device address: 01, function code: 10, register address: 0002, register number: 02, CRC 16 bits: E0 08)

#### 4.1.3 Tare Weight

Using FC10, write 0 to the measure value register directly. This operation writes to volatile memory and is cleared when the unit is powered off.

Host sends: 01 10 00 00 00 02 04 00 00 00 00 F3 AF (Device address: 01, function code: 10, register address: 0000, register number: 02, data bytes: 04, tare data: 00 00 00 00, CRC 16 bits: F3 AF)

Transmitter responds: 01 10 00 00 00 02 41 C8 (Device address: 01, function code: 10, register address: 0000, register number: 02, CRC 16 bits: 41 C8)

#### 4.1.4 Zero Setting

Read the current measuring values in registers 0000-0001 and current offset values in registers 0004-0005, then calculate a new offset value by adding the existing offset to the measured value.

Write the new value into the offset registers 0004-0005.

#### **⚠ CAUTION**

This is a non-volatile operation and should not be performed frequently to preserve chip memory, use of the tare function is strongly recommended

## 5. Calibration

Perform calibration via Modbus RTU protocol by performing the following:

1. With no load applied, read the AD values (register 1F40 & 1F41) 32 times and take the average.
2. Write the average to AVP1 (0008 & 0009) and write 0 to PVP1 (001A & 001B).
3. With a known load applied, read the AD values (register 1F40 & 1F41) 32 times again and take the average.
4. Write the result to AVP2 (000A & 000B) and write the load value to PVP2 (001C & 001D).
5. Select a resolution by writing an appropriate value to PVP2  
 Ex. Applying a 10kg load, writing a value of 10 000 to PVP2 will get a resolution of 10/10 000 = 0.001kg (1g), writing a value of 1000 will get a resolution of 10/1000 = 0.01kg (10g), etc.
6. Write 2 to calibration point number (register 0006 & 0007) to complete calibration.
7. For additional calibration points, repeat steps 3-6 using the additional calibration registers.

## 6. Operation

- The amplifier is not IP rated and must be kept away from water or debris ingress as these can significantly affect the output or render the amplifier inoperable. An enclosure is strongly recommended.
- For the most stable amplifier readouts, a stable and reliable DC power supply should be used.
- The load cell cable should be run through areas free of electrical and magnetic fields as the load cell must be able to transmit signal differences of a few  $\mu\text{V}$  to the amplifier, these fields can induce interference voltages.

## 7. Technical Specifications

### 7.1 Drawings & Dimensions

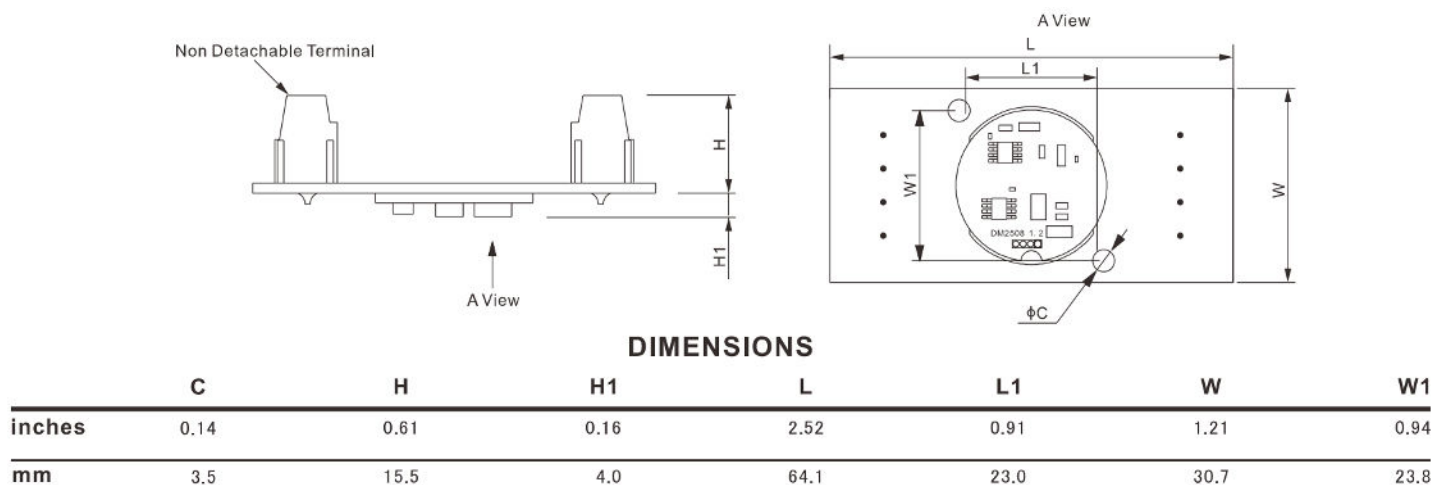


Figure 7-1: Chip Dimensions

## 7.2 Specifications Table

Table 7-1: Product Specifications

|                                     | DGB-DM2507                   | DGB-DM2508 |
|-------------------------------------|------------------------------|------------|
| <b>Acceptable Load Cell Type</b>    | All strain gauge type        |            |
| <b>Weight Approx. (g)</b>           | 19                           |            |
| <b>Power Supply</b>                 | 9~24VDC                      |            |
| <b>Working Temperature</b>          | -22°F – 122°F / -30°C – 50°C |            |
| <b>Output signal</b>                | RS-232                       | RS-485     |
| <b>Output protocol</b>              | Modbus RTU                   |            |
| <b>Non-linearity</b>                | <0.01%                       |            |
| <b>Input range</b>                  | 0.8-3.9mV/V                  |            |
| <b>Power consumption</b>            | 0.36W @ 12V                  |            |
| <b>Load cell excitation voltage</b> | 5V                           |            |

### ■ Important

Specifications are subject to change *without* notice. Users are encouraged to refer to our website or confirm with our team any details, questions, or concerns.

Please **Contact Our Authorized Dealer** for Technical Assistance:

**Notes:**

V1.0.0  
PN-250609

**1-855-269-5623**  
[www.anyload.com](http://www.anyload.com)

© 2025 Anyload Weigh & Measure Inc.  
Specifications subject to change without notice.

**ANYLOAD®**